IEOR165 Discussion Week 7

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Outline



- 1 Nadaraya-Watson Estimator
- 2 Partially Linear Model
- 3 Support Vector Machine

Nadaraya-Watson Estimator: Motivation



Given the data $\{(X_1, Y_1), \dots, (X_n, Y_n)\}$, we want to find the relationship between Y_i (response) and X_i (predictor):

$$Y_i = g(X_i) + \epsilon_i$$

Basically, we find to find $g(x_i)$, which is

$$g(x) = E(Y_i|X_i = x)$$

where we assume $E(\epsilon_i|X_i)=0$.

- Parametric methods: assume the form of g(x), e.g. linear, polynomial, exponential... Then we only need to estimate the parameters that characterize g(x).
- Nonparametric methods: make no assumptions about the form of g(x), which implies the number of parameters is infinite...

An Intuitive Nonparametric Method



K-nearest neighbor average:

$$\begin{split} \hat{g}(x) &= \frac{1}{k} \sum_{X_i \in N_k(x)} Y_i \\ &= \sum_{i=1}^n \frac{I(X_i \in N_k(x))}{k} \cdot Y_i \\ &= \sum_{i=1}^n \frac{I(X_i \in N_k(x))}{\sum_{i=1}^n I(X_i \in N_k(x))} \cdot Y_i \\ &= \frac{\sum_{i=1}^n I(X_i \in N_k(x)) \cdot Y_i}{\sum_{i=1}^n I(X_i \in N_k(x))} \end{split}$$

- You can compare this with our intuitive method for estimating pdf
- Not continuous and indifferentiable

Nadaraya-Watson Estimator



To reach smoothness, replace the indicator function by kernel function

$$\hat{g}(x) = \frac{\sum_{i=1}^{n} K(\frac{X_i - x}{h}) \cdot Y_i}{\sum_{i=1}^{n} K(\frac{X_i - x}{h})}$$

Then we get the Nadaraya-Watson Estimator.

- Weighted average: kernel weights
- Relation to kernel density estimate

$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^{n} K(\frac{X_i - x}{h})$$

$$\hat{f}(x,y) = \frac{1}{nh^2} \sum_{i=1}^{n} K(\frac{X_i - x}{h}) K(\frac{Y_i - y}{h})$$

And by the formula

$$g(x) = E(Y|X=x) = \int y f(y|x) dy = \int y \frac{f(x,y)}{f(x)} dy$$

Nadaraya-Watson Estimator



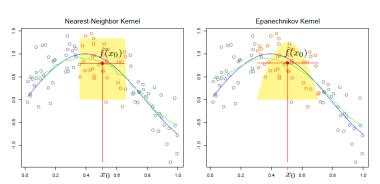


FIGURE 6.1. In each panel 100 pairs x_i , y_i are generated at random from the blue curve with Gaussian errors: $Y = \sin(4X) + \varepsilon$, $X \sim U[0,1]$, $\varepsilon \sim N(0,1/3)$. In the left panel the green curve is the result of a 30-nearest-neighbor running-mean smoother. The red point is the fitted constant $\hat{f}(x_0)$, and the red circles indicate those observations contributing to the fit at x_0 . The solid yellow region indicates the weights assigned to observations. In the right panel, the green curve is the kernel-weighted average, using an Epanechnikov kernel with (half) window width $\lambda = 0.2$.

Partially Linear Model



A compromise between parametric model and nonparametric model

$$Y_i = X_i \beta + g(Z_i) + \epsilon_i$$

- Predictor: (X_i, Z_i)
- A parametric part: linear model
- lacksquare A nonparametric part: $g(Z_i)$
- Estimation:

$$E(Y_i|Z_i) = E(X_i|Z_i)\beta + g(Z_i)$$

$$\Rightarrow Y_i - E(Y_i|Z_i) = (X_i - E(X_i|Z_i))\beta + \epsilon$$

■ For $E(Y_i|Z_i)$ and $E(X_i|Z_i)$, use Nadaraya-Watson Estimators

Classification



When our response is qualitative, or categorical, predicting the response is actually doing classification.

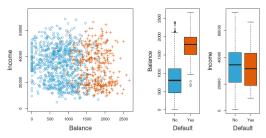


FIGURE 4.1. The Default data set. Left: The annual incomes and monthly credit card balances of a number of individuals. The individuals who defaulted on their credit card payments are shown in orange, and those who did not are shown in blue. Center: Boxplots of balance as a function of default status. Right: Boxplots of income as a function of default status.

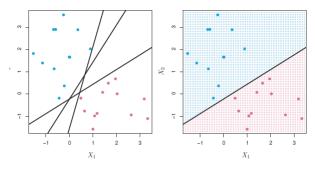
Predictor: Income and Balance (X)

Response: Default or not (Y)

Classification



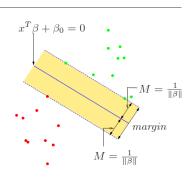
How to classify? Draw a hyperplane $X'\beta + \beta_0 = 0$



IGURE 9.2. Left: There are two classes of observations, shown in blue and purple, each of which has measurements on two variables. Three separating perplanes, out of many possible, are shown in black. Right: A separating hyprlane is shown in black. The blue and purple grid indicates the decision rule ade by a classifier based on this separating hyperplane: a test observation that lls in the blue portion of the grid will be assigned to the blue class, and a test servation that falls into the purple portion of the grid will be assigned to the ryple class.



How to find the optimal hyperplane $X'\beta+\beta_0=0$? when perfectly separable



Objective: Maximize margin = Minimize $||\beta||$ Constraints: separate the data correctly



If
$$X_i'\beta + \beta_0 \ge 1$$
, $y_i = 1$ If $X_i'\beta + \beta_0 \le -1$, $y_i = -1$

So the constraint is

$$y_i(X_i'\beta + \beta_0) \ge 1 \quad \forall i = 1, \dots, n$$

The optimization problem is

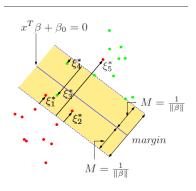
$$\min_{\beta,\beta_0} ||\beta||$$
s.t. $y_i(X_i'\beta + \beta_0) \ge 1 \quad \forall i = 1, \dots, n$

or

$$\min_{\beta,\beta_0} ||\beta||^2$$
s.t. $y_i(X_i'\beta + \beta_0) \ge 1 \quad \forall i = 1,\dots, n$



When not perfectly separable



Objective: Minimize $||\beta||$ and errors

Constraints: separate the data correctly with possible errors



When not perfectly separable, the optimization problem is

$$\min_{\beta,\beta_0} ||\beta||^2 + \lambda \sum_{i=1}^n \xi_i$$
s.t. $y_i(X_i'\beta + \beta_0) \ge 1 - \xi_i \quad \forall i = 1, \dots, n$

$$\xi_i \ge 0 \quad \forall i = 1, \dots, n$$

How to find the dual function? Recall the Lagrangian dual and KKT conditions.

References



- James, G., Witten, D., Hastie, T., & Tibshirani, R. (2013). An introduction to statistical learning (Vol. 112). New York: springer.
- Hastie, T., Tibshirani, R., Friedman, J., & Franklin, J. (2005). The elements of statistical learning: data mining, inference and prediction. The Mathematical Intelligencer, 27(2), 83-85.
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